

**Amendments to the Claims:**

This listing of claims will replace all prior versions, and listings, of claims in the application:

**Listing of Claims:**

1. (Previously presented) An environment measurement method comprising:  
receiving first signals produced in response to a laser beam scattered by said environment;  
receiving second signals produced in response to a radar beam scattered by said environment; and  
storing data representing said first and second signals, wherein storing said data comprises storing measurement context information in association with said data representing said first and second signals.
2. (Original) The method of claim 1 further comprising receiving said laser beam scattered by said environment and producing said first signals in response thereto.
3. (Original) The method of claim 1 further comprising producing an incident laser beam for scattering by said environment to produce said laser beam scattered by said environment.
4. (Previously presented) An environment measurement method comprising:  
receiving first signals produced in response to a laser beam scattered by said environment;  
receiving second signals produced in response to a radar beam scattered by said environment;  
storing data representing said first and second signals;  
producing an incident laser beam for scattering by said environment to produce said laser beam scattered by said environment; and  
directing said incident laser beam to said environment at a desired angle.
5. (Original) The method of claim 4 wherein directing comprises adjusting a physical orientation of a beam directing device in response to an orientation signal, to direct said incident laser beam to said environment at said desired angle.
6. (Original) The method of claim 5 further comprising producing said orientation signal.
7. (Original) The method of claim 5 further comprising directing said laser beam scattered by said environment from said beam directing device to a detector.

8. (Original) The method of claim 2 wherein:
  - receiving said laser beam scattered by said environment comprises receiving scattered portions of a laser pulse scattered by respective portions of said environment; and
  - producing said first signals further comprises continuously producing data signals in response to said scattered portions of said laser pulse, during a measurement interval of sufficient duration to receive all said scattered portions.
9. (Original) The method of claim 1 further comprising producing said second signals in response to said radar beam scattered by said environment.
10. (Original) The method of claim 9 further comprising receiving said radar beam scattered by said environment at an airborne receiver, said radar beam having a wavelength of at least on the order of one meter.
11. (Original) The method of claim 10 wherein receiving comprises receiving, as said radar beam scattered by said environment, a radar beam having a wavelength between 0.7 and 2 meters.
12. (Original) The method of claim 9 further comprising directing an incident radar beam to said environment to produce said radar beam scattered by said environment.
13. (Original) The method of claim 12 wherein directing comprises directing to said environment, as said incident radar beam, an ultra-wide band (UWB) radar beam.
14. (Previously presented) An environment measurement method comprising:
  - receiving first signals produced in response to a laser beam scattered by said environment;
  - receiving second signals produced in response to a radar beam scattered by said environment;
  - storing data representing said first and second signals;
  - producing said second signals in response to said radar beam scattered by said environment;
  - directing an incident radar beam to said environment to produce said radar beam scattered by said environment, wherein directing comprises transmitting said incident radar beam to said environment from a transmission antenna system; and

receiving said radar beam scattered by said environment at a reception antenna system.

15. (Original) The method of claim 14 wherein producing said second signals comprises delaying signals produced by at least some of a plurality of antennae of said reception antenna system.
16. (Original) The method of claim 14 wherein said transmission antenna system and said reception antenna system comprise a common transceiving antenna system, and wherein transmitting and receiving comprise transmitting and receiving at said common transceiving antenna system.
17. (Original) The method of claim 12 further comprising blanking transmitter cross-talk signals while directing said incident radar beam to said environment.
18. (Original) The method of claim 9 wherein producing said second signals comprises producing frequency-shifted signals in response to said radar beam scattered by said environment.
19. (Original) The method of claim 18 wherein producing frequency-shifted signals comprises:  
producing initial electrical signals at frequencies of said radar beam scattered by said environment, in response thereto; and  
applying said initial electrical signals and a mixing frequency signal to a mixer, to produce said frequency-shifted signals.
20. (Original) The method of claim 18 wherein producing frequency-shifted signals comprises producing in-phase frequency-shifted signals and in-quadrature frequency-shifted signals.
21. (Original) The method of claim 18 wherein producing said second signals further comprises digitizing said frequency-shifted signals.
22. (Original) The method of claim 9 further comprising adjustably attenuating said second signals.
23. (Original) The method of claim 1 wherein storing said data comprises defining a data structure comprising a measurement context field for storing measurement context information, a laser field for storing said data representing said first signals, and a radar beam field for storing said data representing said second signals.
24. (Cancelled).
25. (Previously presented) The method of claim 1 wherein storing measurement context information comprises storing global positioning

satellite (GPS) information indicative of a location at which at least one of said laser beam and said radar beam is received.

26. (Previously presented) The method of claim 1 wherein storing measurement context information comprises storing at least one time value indicative of a time at which at least one of said laser beam and said radar beam is received.
27. (Previously presented) The method of claim 1 wherein storing measurement context information comprises storing attenuation information indicative of an amount of attenuation of said second signals.
28. (Previously presented) The method of claim 1 wherein storing measurement context information comprises storing a frequency value indicative of a frequency of said radar beam.
29. (Previously presented) The method of claim 1 wherein storing measurement context information comprises storing user-inputted information.
30. (Original) The method of claim 29 wherein storing measurement context information comprises storing a flight line indication indicative of a flight line over which said laser beam and said radar beam are received by an airborne environment measurement system.
31. (Previously presented) An environment measurement method comprising:
  - receiving first signals produced in response to a laser beam scattered by said environment;
  - receiving second signals produced in response to a radar beam scattered by said environment; and
  - storing data representing said first and second signals, wherein storing said data representing said second signals comprises storing an in-phase value and an in-quadrature value representing an in-phase component and an in-quadrature component respectively of said second signals.
32. (Previously presented) The method of claim 1 further comprising producing a representation of said environment in response to said data.
33. (Original) The method of claim 32 wherein producing said representation comprises applying a migration algorithm to said data representing said second signals, to associate said data representing said second signals with particular locations of said environment.

34. (Currently Amended) ~~The method of claim 35 wherein producing said representation comprises identifying a foliage height of said environment~~ An environment measurement method comprising:  
receiving first signals produced in response to a laser beam scattered by said environment;  
receiving second signals produced in response to a radar beam scattered by said environment;  
storing data representing said first and second signals; and  
producing a representation of said environment in response to said data, wherein producing said representation comprises identifying a height of a terrain surface of said environment.

35. (Currently Amended) ~~An environment measurement method comprising:~~  
~~receiving first signals produced in response to a laser beam scattered by said environment;~~  
~~receiving second signals produced in response to a radar beam scattered by said environment;~~  
~~storing data representing said first and second signals; and~~  
~~producing a representation of said environment in response to said data, wherein producing said representation comprises identifying a height of a terrain surface of said environment..~~ The method of claim 34 wherein producing said representation comprises identifying a foliage height of said environment.

36. (Currently Amended) The method of claim [35] 34 wherein producing said representation further comprises identifying features of said environment below said terrain surface.

37. (Currently Amended) The method of claim[35] 34 wherein producing said representation further comprises identifying a slope of said terrain surface.

38. (Original) The method of claim 32 wherein producing said representation comprises producing a digital elevation model of said environment.

39. (Original) The method of claim 32 wherein producing said representation comprises producing at least one contour representation of said environment.

40. (Previously presented) An environment measurement system comprising:

a memory device; and

a processor circuit in communication with said memory device, wherein said processor circuit is configured to receive first signals produced in response to a laser beam scattered by said environment, to receive second signals produced in response to a radar beam scattered by said environment, to store data representing said first and second signals in said memory device, and to store measurement context information in said memory device in association with said data representing said first and second signals.

41. (Previously presented) The system of claim 40 further comprising a detector to receive said laser beam scattered by said environment and to produce said first signals in response thereto.
42. (Previously presented) The system of claim 40 further comprising a laser to produce an incident laser beam for scattering by said environment to produce said laser beam scattered by said environment.
43. (Previously presented) An environment measurement system comprising:
  - a memory device;
  - a processor circuit in communication with said memory device, wherein said processor circuit is configured to receive first signals produced in response to a laser beam scattered by said environment, to receive second signals produced in response to a radar beam scattered by said environment, and to store data representing said first and second signals in said memory device;
  - a laser to produce an incident laser beam for scattering by said environment to produce said laser beam scattered by said environment; and
  - a beam directing device to direct said incident laser beam to said environment at a desired angle.
44. (Previously presented) The system of claim 43 further comprising a motion mechanism to adjust a physical orientation of said beam directing device in response to an orientation signal, to direct said incident laser beam to said environment at said desired angle.
45. (Previously presented) The system of claim 44 further comprising an orientation monitoring device to produce said orientation signal.
46. (Original) The system of claim 43 wherein said beam directing device is locatable to direct said laser beam scattered by said environment to said detector.

47. (Previously presented) The system of claim 41 further comprising an analog-to-digital converter (ADC) to cooperate with said detector to continuously produce data signals in response to scattered portions of a laser pulse scattered by respective portions of said environment, during a measurement interval of sufficient duration to receive all said scattered portions.
48. (Previously presented) The system of claim 40 further comprising a radar system to produce said second signals in response to said radar beam scattered by said environment.
49. (Original) The system of claim 48 further wherein said radar system comprises an airborne radar reception system configured to receive, as said radar beam scattered by said environment, a radar beam having a wavelength of at least on the order of one meter.
50. (Original) The system of claim 49 wherein said airborne radar reception system is configured to receive, as said radar beam scattered by said environment, a radar beam having a wavelength between 0.7 and 2 meters.
51. (Original) The system of claim 48 wherein said radar system is configured to direct an incident radar beam to said environment to produce said radar beam scattered by said environment.
52. (Original) The system of claim 51 wherein said radar system is configured to direct to said environment, as said incident radar beam, an ultra-wide band (UWB) radar beam.
53. (Previously presented) An environment measurement system comprising:
  - a memory device; and
  - a processor circuit in communication with said memory device, wherein said processor circuit is configured to receive first signals produced in response to a laser beam scattered by said environment, to receive second signals produced in response to a radar beam scattered by said environment, and to store data representing said first and second signals in said memory device;
  - a radar system to produce said second signals in response to said radar beam scattered by said environment, wherein said radar system is configured to direct an incident radar beam to said environment to produce said radar beam scattered by said environment, and wherein said radar system comprises a transmission antenna system configured to direct said incident radar beam and a reception antenna system configured to receive said radar beam scattered by said environment.

54. (Previously presented) The system of claim 53 wherein said radar system further comprises a delay device to delay signals produced by at least some of a plurality of antennae of said reception antenna system.
55. (Original) The system of claim 53 wherein said transmission antenna system and said reception antenna system comprise a common transceiving antenna system.
56. (Previously presented) The system of claim 51 wherein said radar system further comprises a blanker to blank transmitter cross-talk signals while directing said incident radar beam to said environment.
57. (Previously presented) The system of claim 48 wherein said radar system further comprises a frequency-shifter to produce said second signals by producing frequency-shifted signals in response to said radar beam scattered by said environment.
58. (Previously presented) The system of claim 57 wherein:  
said radar system is configured to produce initial electrical signals at frequencies of said radar beam scattered by said environment, in response thereto; and  
said frequency-shifter comprises a mixer to produce said frequency-shifted signals in response to said initial electrical signals and a mixing frequency signal.
59. (Previously presented) The system of claim 57 wherein said frequency-shifter comprises at least one mixer and at least one phase-shifter, and is to produce, as said frequency-shifted signals, in-phase frequency-shifted signals and in-quadrature frequency-shifted signals.
60. (Previously presented) The system of claim 57 further comprising an analog-to-digital converter (ADC) to digitize said frequency-shifted signals.
61. (Previously presented) The system of claim 48 further comprising an attenuator to adjustably attenuate said second signals.
62. (Original) The system of claim 40 wherein said processor circuit is configured to define, in said memory device, a data structure comprising a measurement context field for storing measurement context information, a laser field for storing said data representing said first signals, and a radar beam field for storing said data representing said second signals.
63. (Cancelled).
64. (Previously presented) The system of claim 40 wherein said processor circuit is configured to store, as said measurement context information,

global positioning satellite (GPS) information indicative of a location at which at least one of said laser beam and said radar beam is received.

65. (Previously presented) The system of claim 40 wherein said processor circuit is configured to store, as said measurement context information, at least one time value indicative of a time at which at least one of said laser beam and said radar beam is received.
66. (Previously presented) The system of claim 40 wherein said processor circuit is configured to store, as said measurement context information, attenuation information indicative of an amount of attenuation of said second signals.
67. (Previously presented) The system of claim 40 wherein said processor circuit is configured to store, as said measurement context information, a frequency value indicative of a frequency of said radar beam.
68. (Previously presented) The system of claim 40 wherein said processor circuit is configured to store, as said measurement context information, user-inputted information.
69. (Original) The system of claim 68 wherein said processor circuit is configured to store, as said measurement context information, a flight line indication indicative of a flight line over which said laser beam and said radar beam are received by an airborne environment measurement system.
70. (Previously presented) An environment measurement system comprising:
  - a memory device; and
  - a processor circuit in communication with said memory device, wherein said processor circuit is configured to receive first signals produced in response to a laser beam scattered by said environment, to receive second signals produced in response to a radar beam scattered by said environment, and to store data representing said first and second signals in said memory device, and wherein said processor circuit is configured to store, as said data representing said second signals, an in-phase value and an in-quadrature value representing an in-phase component and an in-quadrature component respectively of said second signals.
71. (Previously presented) The system of claim 40 further comprising a representation processing circuit configured to produce a representation of said environment in response to said data.
72. (Original) The system of claim 71 wherein said representation processing circuit is configured to apply a migration algorithm to said data representing said second signals, to associate said data

representing said second signals with particular locations of said environment.

73. (Previously presented) The system of claim 74 wherein said representation processing circuit is configured to identify a foliage height of said environment.
74. (Previously presented) An environment measurement system comprising:
  - a memory device;
  - a processor circuit in communication with said memory device, wherein said processor circuit is configured to receive first signals produced in response to a laser beam scattered by said environment, to receive second signals produced in response to a radar beam scattered by said environment, and to store data representing said first and second signals in said memory device; and
  - a representation processing circuit configured to produce a representation of said environment in response to said data, wherein said representation processing circuit is configured to identify a height of a terrain surface of said environment.
75. (Original) The system of claim 74 wherein said representation processing circuit is configured to identify features of said environment below said terrain surface.
76. (Original) The system of claim 74 wherein said representation processing circuit is configured to identify a slope of said terrain surface.
77. (Original) The system of claim 71 wherein said representation processing circuit is configured to produce a digital elevation model of said environment.
78. (Original) The system of claim 71 wherein said representation processing circuit is configured to produce at least one contour representation of said environment.
79. (Original) The system of claim 71 wherein said representation processing circuit comprises said processor circuit.
80. (Previously presented) An environment measurement system comprising:
  - means for receiving first signals produced in response to a laser beam scattered by said environment;
  - means for receiving second signals produced in response to a radar beam scattered by said environment; and

means for storing data representing said first and second signals, said means for storing comprising means for storing measurement context information in association with said data representing said first and second signals.

81. (Previously presented) A computer-readable medium storing codes for directing a processor circuit to:

receive first signals produced in response to a laser beam scattered by said environment;

receive second signals produced in response to a radar beam scattered by said environment; and

store data representing said first and second signals, and store measurement context information in association with said data representing said first and second signals.

82. (Previously presented) A signal embodied in a computer-readable medium, the signal comprising:

a first code segment for directing a processor circuit to receive first signals produced in response to a laser beam scattered by said environment;

a second code segment for directing said processor circuit to receive second signals produced in response to a radar beam scattered by said environment; and

a third code segment for directing said processor circuit to store data representing said first and second signals and to store measurement context information in association with said data representing said first and second signals.

83. (Cancelled).

84. (Cancelled).

85. (Previously presented) An environment measurement method comprising:

continuously producing data in response to scattered portions of a laser pulse scattered by respective portions of said environment, during a measurement interval of sufficient duration to receive all said scattered portions; and

storing said data.

86. (Original) The method of claim 85 wherein said measurement interval is at least on the order of one microsecond.

87. (Original) The method of claim 85 further comprising producing an incident laser pulse having a duration on the order of one nanosecond, for scattering by said environment to produce said scattered portions of said laser pulse.
88. (Original) The method of claim 85 further comprising:  
receiving said incident laser pulse at a beam directing device; and  
adjusting a physical orientation of said beam directing device in response to an orientation signal, to direct said incident laser pulse from said beam directing device to said environment.
89. (Previously presented) An environment measurement system comprising:  
a memory device; and  
a processor circuit in communication with said memory device, wherein said processor circuit is configured to:  
cooperate with a detection system to continuously produce data in response to scattered portions of a laser pulse scattered by respective portions of said environment, during a measurement interval of sufficient duration to receive all said scattered portions, and  
store said data in said memory device.
90. (Original) The system of claim 89 further comprising said detection system.
91. (Previously presented) The system of claim 90 wherein said detection system comprises:  
a detector to receive said scattered portions and to produce analog signals in response thereto; and  
an analog-to-digital converter (ADC) to cooperate with said detector to continuously produce digital signals in response to said analog signals, during said measurement interval.
92. (Original) The system of claim 89 wherein said processor circuit is configured to define said duration of said measurement interval to be at least on the order of one microsecond.
93. (Previously presented) The system of claim 89 further comprising a laser to produce an incident laser pulse having a duration on the order of one nanosecond, for scattering by said environment to produce said scattered portions of said laser pulse.
94. (Previously presented) The system of claim 89 further comprising:

a beam directing device locatable to receive said incident laser pulse; and

a motion mechanism to adjust a physical orientation of said beam directing device in response to an orientation signal, to direct said incident laser pulse from said beam directing device to said environment.

95. (Previously presented) An environment measurement system comprising:

means for continuously producing data in response to scattered portions of a laser pulse scattered by respective portions of said environment, during a measurement interval of sufficient duration to receive all said scattered portions; and

means for storing said data.

96. (Previously presented) A computer-readable medium storing codes for directing a processor circuit to:

cooperate with a detection system to continuously produce data in response to scattered portions of a laser pulse scattered by respective portions of said environment, during a measurement interval of sufficient duration to receive all said scattered portions, and

store said data.

97. (Previously presented) A signal embodied in a computer-readable medium, the signal comprising:

a first code segment for directing a processor circuit to cooperate with a detection system to continuously produce data in response to scattered portions of a laser pulse scattered by respective portions of said environment, during a measurement interval of sufficient duration to receive all said scattered portions, and

a second code segment for directing said processor circuit to store said data.

98. (Previously presented) An environment measurement method comprising:

producing signals in response to a radar beam scattered by said environment and received at an airborne receiver, said radar beam having a wavelength of at least on the order of one meter, wherein producing signals comprises continuously producing data signals in response to scattered portions of a radar pulse scattered by respective portions of said environment, during a measurement interval of sufficient duration to receive all said scattered portions; and

storing data representing said signals.

99. (Original) The method of claim 98 further comprising receiving said radar beam scattered by said environment at said airborne receiver, said radar beam having a wavelength between 0.7 and 2 meters.
100. (Cancelled).
101. (Original) The method of claim 98 further comprising directing an ultra-wide band (UWB) incident radar beam to said environment to produce said radar beam scattered by said environment.
102. (Previously presented) An environment measurement system comprising:  
  
an airborne radar reception system to produce signals in response to a radar beam scattered by said environment and having a wavelength of at least on the order of one meter, wherein said airborne radar reception system is to continuously produce data signals in response to scattered portions of a radar pulse scattered by respective portions of said environment, during a measurement interval of sufficient duration to receive all said scattered portions; and  
  
a processor circuit in communication with said airborne radar reception system, configured to store data representing said signals.
103. (Original) The system of claim 102 wherein said airborne radar reception system is configured to receive, as said radar beam scattered by said environment, a radar beam having a wavelength between 0.7 and 2 meters.
104. (Cancelled).
105. (Previously presented) The system of claim 102 wherein said airborne radar reception system comprises:  
  
a detector to receive said scattered portions and to produce analog signals in response thereto; and  
  
an analog-to-digital converter (ADC) to cooperate with said detector to continuously produce digital signals in response to said analog signals, during said measurement interval.
106. (Previously presented) The system of claim 102 further comprising a radar transmission system to direct an ultra-wide band (UWB) incident radar beam to said environment to produce said radar beam scattered by said environment.
107. (Previously presented) An environment measurement system comprising:

means for producing signals in response to a radar beam scattered by said environment and received at an airborne receiver, said radar beam having a wavelength of at least on the order of one meter, wherein said means for producing signals comprises means for continuously producing data signals in response to scattered portions of a radar pulse scattered by respective portions of said environment, during a measurement interval of sufficient duration to receive all said scattered portions; and

means for storing data representing said signals.

108. (Currently amended) An environment measurement method comprising:

receiving data representing signals produced at an airborne receiver in response to a radar beam scattered by said environment; and

| applying a time domain migration algorithm to said data, to associate said data with particular locations of said environment.

109. (Currently amended) An environment measurement system comprising:

a memory device; and

a processor circuit in communication with said memory device, wherein said processor circuit is configured to:

receive data representing signals produced at an airborne receiver in response to a radar beam scattered by said environment; and

| apply a time domain migration algorithm to said data, to associate said data with particular locations of said environment.

110. (Currently amended) An environment measurement system comprising:

means for receiving data representing signals produced at an airborne receiver in response to a radar beam scattered by said environment; and

| means for applying a time domain migration algorithm to said data, to associate said data with particular locations of said environment.

111. (Currently amended) A computer-readable medium storing codes for directing a processor circuit to:

receive data representing signals produced at an airborne receiver in response to a radar beam scattered by said environment; and

| apply a time domain migration algorithm to said data, to associate said data with particular locations of said environment.

112. (Currently amended) A signal embodied in a computer-readable medium, the signal comprising:

a first code segment for directing a processor circuit to receive data representing signals produced at an airborne receiver in response to a radar beam scattered by said environment; and

a second code segment for directing a processor circuit to apply a time domain migration algorithm to said data, to associate said data with particular locations of said environment.